

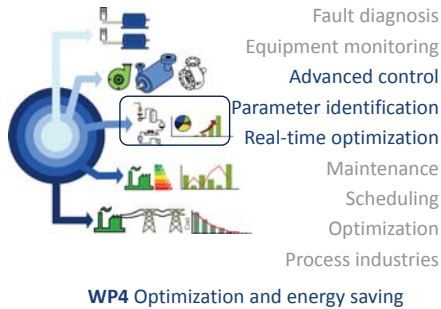
Electrical Drives for Compressors – Work Package 4

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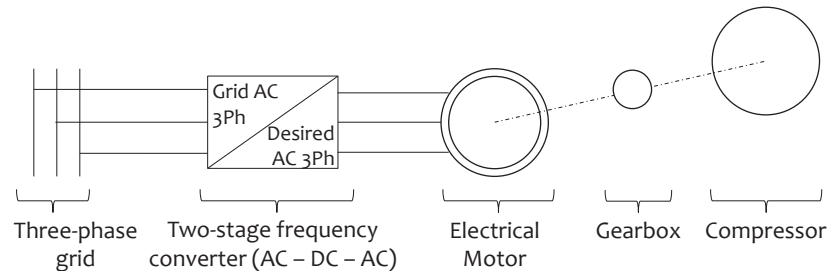
WP4 in Energy Smartops

Aim: Develop control techniques for electrical drives for compressors which minimize the power loss:

- Focus on a single machine, with the goal of delivering a desired torque for some process (e.g., taking inputs from WP2)
- Real-time implementation, which allows on-line computations
- Advanced power losses modelling, to account for more loss sources



A generic framework for compression systems



3-phase grid 3-phase inverters Electrical Motor Mechanical Load

- | | | | |
|---|--|--|---|
| <ul style="list-style-type: none"> - Three-phase voltages at typical frequencies of 50-60Hz (EU-US), - Variable speed control is not possible if the drive is directly connected to grid; | <ul style="list-style-type: none"> - 6-switch voltage source inverters to realize the desired voltage, - Frequency and magnitude are important control parameters; | <ul style="list-style-type: none"> - Among available technologies, we currently focus on induction motors, - Field Oriented Control for high performance and efficiency; | <ul style="list-style-type: none"> - Focus on industrial pumps and compressors moved by the electrical motor, - Model suitable for real-time control is hard to derive; |
|---|--|--|---|

Optimization of electrical drives

- Development of accurate losses models and optimization schemes for electrical motors
- Design of robust control algorithm to take into account uncertainties and performance bounds
- Preliminary experimental results suggest that our steady-state optimization approach:
 - Reduces power losses up to 20% on the tested 1HP induction motor
 - Allows one to reduce thermal stress and/or increase the machine rating substantially
 - Improves the efficiency at nominal conditions of 3%

Control of compressors

- Derivation of a compressor model, suitable for embedded platforms
- Design of several controllers for compressors, suitable for embedded platforms, as PI control, backstepping control and Model Predictive Control
- Extension of the feasible operating regions to include potentially unstable points (due to surge phenomena), by opportunely controlling the recycle anti-surge valve
- Substantially improvements w.r.t. state of the art controls

EARLY STAGE RESEARCHERS IN WORK PACKAGE 4

Giampaolo Torrisi (ETH Zurich)



Loss modelling of electrical drives and MPC of compressors

Bart Van Parys (ETH Zurich)



Robust control of dynamical systems

Alejandro F. Gomez (TU Cracow)



Compressor modeling for real-time applications

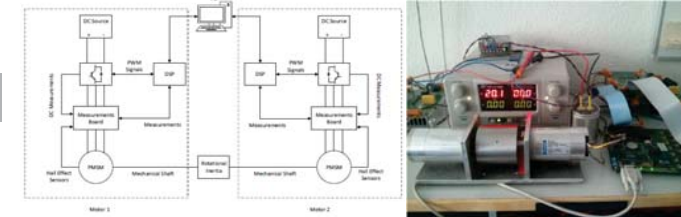
Victor Jaramillo V. (ABB PL)



Control of compressor and optimization of PM motors

ETH case study

- An experimental test rig is employed to validate the theoretical results
- The test bench is made of two motors whose shafts are connected to each other
- Each of the motors is controlled by a DSP board, programmable in C. The data acquisition system allows us to take measurements of the input voltages and currents



Type	Unit	Value
Number of pole pairs	-	4
Nominal voltage	V DC	48
Nominal speed	Rpm	4000
Nominal torque	N m	0.36
Nominal current	A	4.5
Nominal output power	W	150
No-load speed	Rpm	6800
Rotor moment of inertia	Kg m ²	19 · 10 ⁻⁶



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Energy-SmartOps consortium investigates equipment and process monitoring, integrated automation and optimization for energy savings. <http://www.energy-smartops.eu/>