

Particle Symmetries

- Particle physics
- Lie groups, Lie Algebras
- Repⁿ Theory

Books:

- 512-2/54
- Fulton and Harris - v. mathematical
 - Georgi } more physics
 - Jones }
 - Cahn
 - Ramond

1. Particles, The Standard Model

- In the SM we have:

- quarks } 3 generations
- leptons }
- gauge bosons
- Higgs boson
- Forces: strong nuclear, EM, weak
→ gravity is outside the SM

- Gauge principle: $\underbrace{SU(3)}_{\text{colour}} \times \underbrace{SU(2) \times U(1)}_{\text{EW}}$
8 gluons $W^{\pm}, Z^0, \gamma$

- What is $SU(3)$?

→ Special unitary gp. of 3×3 matrices

- $SU(N)$: $N \times N$ complex matrices (unitary) of $\det 1$.
- $U(1)$: unitary group of $\dim 1$, $e^{i\alpha}$ $\alpha \in [0, 2\pi)$.

- We characterise these particles with:

Gauge symmetries

- spin : matter spin $1/2$; spin 0 Higgs; Spin 1 gauge b.
- mass
- charge $\rightarrow$ irreducible repⁿ.

- Beyond the SM : graviton spin 2
gravitino spin $3/2$.

- Spin - irreducible repⁿ under $SU(2)$.

- Mass - gluon : 0

W, Z : 100 GeV

γ : 0

quarks : u, d, c, s, t, b

1 MeV 1 GeV 500 MeV 200 GeV 10 GeV

} Spontaneous Symmetry breaking

generations

$2/3 e$	u	c	t	} spin under $SU(2)$
$-1/3 e$	d	s	b	

- Quarks come in doublets and have colour charge.

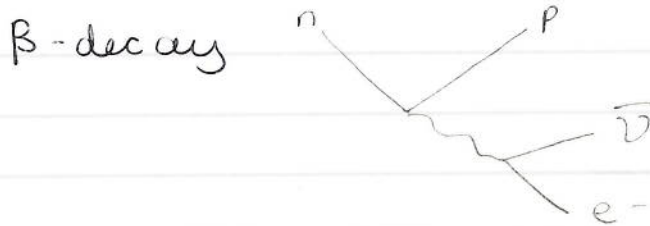
$\rightarrow$ 3 colour states

$\rightarrow$ antiquarks.

- They also possess charge.

Global Symmetries

- Spacetime symmetries. eg. Lorentz, discrete sym.
- lepton no. eg. e^-



- lepton no.
 - charge
 - baryon no.
- are all preserved.

- Baryon no. : for each quark, the baryon no. is $\frac{1}{3}$.
- Isospin : $\begin{pmatrix} u \\ d \end{pmatrix}$ transform in spin $\frac{1}{2}$. We say $\begin{pmatrix} u \\ d \end{pmatrix}^{+1}$.
- Flavour symmetry : 3 light quarks $\Rightarrow$ interactions governed by $\approx SU(3)$ symmetry.

Spacetime Symmetries

- Spacetime translations
→ momentum and energy are conserved.
→ **Noether's Theorem**
 - Rotations
→ ang. mom. conserv.
 - Boosts
- } Lorentz transform, 6 total

- Poincaré - 10 symmetries total.
- These are all global symmetries when there's no gravity, but gauge sym. when gravity is turned on.
→ Gravity is the gauge principle of ST sym.

Discrete Symmetries

- Parity P - space reversal $\underline{x} \rightarrow -\underline{x}$
→ broken by Weak interactions.
- Charge conjugation C , matter $\rightarrow$ antimatter
→ K-physics breaks CP sym. (also breaks T).
- Time Reversal T , $t \rightarrow -t$
→ CPT theorem - CPT is conserved for all processes.

CP is only lightly broken - need more violation to explain matter - antimatter asymmetry.

2. Groups

Defⁿ: A gp. is a set^G of elements $g \in G$ s.t. four pts are satisfied, w/ a binary form $G \times G \rightarrow G$ $(\cdot, \cdot)$

1. Closure $g_1, g_2 \in G$, then $g_1 \cdot g_2 \in G$.
2. Associativity $g_1, g_2, g_3 \in G$ then,

$$(g_1 \cdot g_2) \cdot g_3 = g_1 \cdot (g_2 \cdot g_3)$$

3. Identity $e \in G, g \in G$, then $e \cdot g = g \cdot e = g$.

4. Inverse $\forall g \in G \exists ! g^{-1}$ s.t. $g \cdot g^{-1} = g^{-1} \cdot g = e$.
 $\downarrow$ unique

Examples

- Let n be an integer, and $n > 0$, then $\exists GL(n, \mathbb{C})$
 $\rightarrow$ gp. of linear transf. in $\mathbb{C}^n$.

- $GL(n, \mathbb{C})$ is the set of $n \times n$ complex matrices w/ $\det \neq 0$.

- $g \in GL(n, \mathbb{C})$ is then $g_{n \times n}$, $\det g \neq 0$.

- Also have $GL(n, \mathbb{R})$.
 $\rightarrow$ real matrices

- No. of parameters (or the dimension) is n^2 .

- $SL(n, \mathbb{C})$ is a gp. of $GL(n, \mathbb{C})$ matrices w/ $\det = +1$.

$\rightarrow$ "S" = "special".

$\rightarrow$ no. of parameters = $n^2 - 1$. (for $\mathbb{C}$ or $\mathbb{R}$).

$\rightarrow SL(n, \mathbb{C}) \subseteq GL(n, \mathbb{C})$.

E.g. $GL(2, \mathbb{C}) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix}, a, b, c, d \in \mathbb{C}, \right.$
 $\left. ad - bc \neq 0 \right\}$

$$SL(2, \mathbb{Q}) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \text{ s.t. } ad - bc = 1 \right\}.$$

2.1 Rotation Groups

- Consider a vec. space $\mathbb{R}^n$, $\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n$ and $x_i \in \mathbb{R}$. ↗ = $\underline{v}$

- Define length, $L^2 = \sum_{i=1}^n x_i^2 = \underline{v}^T \underline{v}$.

- Consider the set of transformations, which preserve the length, $M \in GL(n, \mathbb{R})$.

ie. $\underline{v}' = M \underline{v}$

length of $\underline{v}'$: $L^2 = \underline{v}'^T M^T M \underline{v} = \underline{v}^T \underline{v}$ preserve length

$\Rightarrow M^T M = \mathbb{1}_{n \times n}$ orthogonal matrix

Start w/
 n^2 . Then remove
 n due to
 $M^T M = \mathbb{1}_{n \times n}$
 $\rightarrow$ have n
constraints.

Orthogonal matrices preserve the length of vector.

$\rightarrow$ group $O(n)$.

$\rightarrow \dim O(n) = \frac{n(n-1)}{2} = n^2 - \frac{n(n+1)}{2}$

E.g. 3×3  6 entries $\frac{n(n+1)}{2}$ for $M^T M = \mathbb{1}$

- $\det(M^T M) = \det M^T \det M = (\det M)^2 = 1$

$$\Rightarrow \det M = \pm 1.$$

- Define $SO(n)$ as the set of $O(n)$ matrices w/ $\det +1$.

E.g. $SO(2) \rightarrow$ rotations in a plane
 $\rightarrow$ one dim, θ

$$\Rightarrow \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}, \quad \theta \in [0, 2\pi).$$

$$SO(3) \rightarrow 3 \text{ angles as } \frac{3(3-1)}{2} = 3$$

- Take a complex vector space $\mathbb{C}^n$, $v = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$,
 $x_i \in \mathbb{C}$.

$$L^2 = \sum_{i=1}^n |x_i|^2 = v^\dagger v.$$

What is the set of ~~complex~~ length preserving transformations in $\mathbb{C}^n$? Given by,

$$v' = Mv, \quad M \in GL(n, \mathbb{C}).$$

$$\begin{aligned} L^2 &= v'^\dagger v' \\ &= v^\dagger M^\dagger M v = v^\dagger v \end{aligned}$$

$$\Rightarrow M^\dagger M = \mathbb{1}_{n \times n}$$

M unitary

the product is

$$\Rightarrow (M^\dagger M)^\dagger = M^\dagger M \Rightarrow \text{Hermitian}$$

$$\dim_{\mathbb{R}} U(n) = n^2$$

E.g. $U(2)$ is the set of 2×2 unitary matrices:

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}, a, b, c, d \in \mathbb{C}.$$

or $\begin{pmatrix} a+id & b+ic \\ b-ic & a-id \end{pmatrix} \rightarrow$ most general way to write this. Check!

Let h be Hermitian and 2×2 :

$$h = \begin{pmatrix} a & b-ic \\ b+ic & d \end{pmatrix} \quad a, b, c, d \in \mathbb{R}.$$

- $SU(n)$ is the set of $U(n)$ matrices w/ $\det = 1$.

Suppose $M \in U(n)$, then $M^\dagger M = \mathbb{1}$.

$$\Rightarrow \det M = e^{i\alpha}, \quad \alpha \in [0, 2\pi)$$

$$\text{as } \det M^\dagger \det M = (\det M)^* (\det M)$$

$$= |\det M|^2 = 1$$

$\Rightarrow \det M$ is a phase.

- Det. is discrete set for $O(n)$, but a whole parameter space for $U(n)$.

$$\Rightarrow \dim \text{SU}(n) = n^2 - 1 \quad \rightarrow \text{as } \alpha = 0$$

- $\text{Sp}(n)$ - symplectic matrices.

$$\text{Set } \eta = \begin{pmatrix} 0_{n \times n} & 1_{n \times n} \\ -1_{n \times n} & 0_{n \times n} \end{pmatrix} \Rightarrow 2n \times 2n \text{ matrix}$$

$$\text{length } L^2 = V^T \cdot \eta \cdot V, \quad V = \begin{pmatrix} x_1 \\ \vdots \\ x_{2n} \end{pmatrix}, \quad x_i \in \mathbb{R}.$$

Linear transf. $M \in \text{GL}(2n, \mathbb{R})$

$$\rightarrow M^T \eta M = \eta \quad \text{symplectic form}$$

$\text{Sp}(n, \mathbb{R})$ is the set of matrices in $\text{GL}(2n, \mathbb{R})$ which satisfies the above condition.

E.g. Phase space, symplectic forms, Poisson brackets, generalised coord.

$$\text{N.B. } M^T \Omega M = \Omega, \quad \Omega = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

$$(M^T \Omega M)^T = M^T \Omega^T M = \Omega^T$$

$$\Rightarrow \Omega^T = -\Omega$$

$\Rightarrow$ antisymmetric form

$$\Rightarrow \text{no. of relations} = \frac{2n(2n-1)}{2}$$

- In $O(n)$ preserves the sym. form; $Sp(n)$ preserves the antisym. form.

$$\dim Sp(n) = n(2n+1) \quad (\text{as } (2n)^2 - \text{no. of relations} = \dim)$$

- The gps. discussed are called **classical gps.**
- Extension of rotation gps.:

$$\eta = \begin{pmatrix} \overset{p}{\text{ones}} & \\ & \underset{q}{\text{minus ones}} \end{pmatrix}$$

$\Rightarrow p+q$ rows and columns.

Then have $O^T \eta O = \eta$ and $O(p, q)$ is the gp. matrix that preserves the length.

$$\text{If } v \in \mathbb{R}^{p+q}, \quad v = \begin{pmatrix} x_1 \\ \vdots \\ x_p \\ y_1 \\ \vdots \\ y_q \end{pmatrix}$$

$$\Rightarrow L^2 = v^T \eta v = \sum_{i=1}^p x_i^2 - \sum_{j=1}^q y_j^2$$

This type of form is used in Special Rel.
 $\Rightarrow SO(3, 1)$ and some discrete extensions of it.

- The Lorentz gp. is an extension of the rotation group.

Properties of the Classical Groups

1. $GL(n, \mathbb{C})$ - $n \times n$ matrices, $\det \neq 0$.

Dimension / no. of parameters = n^2 .

2. $SL(n, \mathbb{C}) \subset GL(n, \mathbb{C})$ w/ $\det = +1$.

Dimension = $\underbrace{n^2 - 1}$

why (-1) ?

We have only one constraint on the matrices: that $\det = 1$. The $\det$ condition is just one constraining relation $\Rightarrow n^2 - 1$.

3. $O(n)$ - $n \times n$ matrices, $\det = \pm 1$, length preserving.

Dimension = $\frac{n(n-1)}{2}$ why?

For $M \in O(n)$ we have the orthogonality condition:

$$M^T M = \mathbb{1}_{n \times n}.$$

So for $M^T M$ we have n^2 entries, which are n^2 eqn's as each element of $M^T M$ must be equal to an entry in $\mathbb{1}_{n \times n}$.

However, only $\frac{n(n+1)}{2}$ of the equⁿs are independ.

(as some of the entries in $M^T M$ are repeated).

$$\Rightarrow \dim. O(n) = n^2 - \frac{n(n+1)}{2}$$

$\uparrow$ $\uparrow$
total no. no. of independ.
of entries equⁿs

$$= \frac{n(n-1)}{2}$$

E.g. let $M \in O(3) \Rightarrow M = \begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{pmatrix}$
 $\Rightarrow M^T = \begin{pmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{pmatrix}$

$$11. = M M^T = \begin{pmatrix} a_1^2 + b_1^2 + c_1^2 & a_1 a_2 + b_1 b_2 + c_1 c_2 & a_3 a_1 + b_3 b_1 + c_3 c_1 \\ a_1 a_2 + b_1 b_2 + c_1 c_2 & a_2^2 + b_2^2 + c_2^2 & a_2 a_3 + b_2 b_3 + c_2 c_3 \\ a_3 a_1 + b_3 b_1 + c_3 c_1 & a_3 a_2 + b_3 b_2 + c_3 c_2 & a_3^2 + b_3^2 + c_3^2 \end{pmatrix}$$

$$\rightarrow n^2 \text{ equⁿs} = 9 \text{ equⁿs}$$

$$\rightarrow \frac{n(n+1)}{2} \text{ independ.} = \frac{3(3+1)}{2} = 6 \quad (\text{ie. 3 repeated equⁿs})$$

$$\rightarrow \dim O(3) = 3$$

For $n=4$, we have 16 equⁿs, but only $\frac{4 \cdot 5}{2} = 10$ are independ.

$$\rightarrow \dim. O(4) = 6.$$

~

A special subgroup of $O(n)$ is $SO(n)$. The $SO(n)$ matrices are $n \times n$ matrices with $\det = +1$.

The dimension of $SO(n)$ is the same as for $O(n)$. This is because the same constraints apply to both $O(n)$ and $SO(n)$ i.e. there are no additional constraints.

4. $U(n)$ - $n \times n$ matrices w/ complex entries, $|\det M|^2 = 1$, length preserving in $\mathbb{C}^n$.

As $|\det M|^2 = 1 \Rightarrow \det M = e^{i\alpha}$ for $\alpha \in [0, 2\pi)$.

i.e. the det. of $U(n)$ matrices are phases.

$M \in U(n)$ must also satisfy:

$$M^\dagger M = \mathbb{1}_{n \times n}$$

$$\Rightarrow \dim_{\mathbb{R}} U(n) = n^2$$

Why? E.g. $U(2)$:

$$M \in U(2) \Rightarrow M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}; M^\dagger = \begin{pmatrix} a^* & c^* \\ b^* & d^* \end{pmatrix}$$

$$M^\dagger M = \begin{pmatrix} |a|^2 + |c|^2 & a^*b + c^*d \\ b^*a + d^*c & |b|^2 + |d|^2 \end{pmatrix} = \mathbb{1}_{2 \times 2}$$

$$4 \text{ eqn's} = (2)^2 = (n)^2.$$

Note that the product $(M^\dagger M)$ is Hermitian:

$$(M^\dagger M)^\dagger = M^\dagger M = \mathbb{1}$$

A special case of $U(n)$ is the subgroup $SU(n)$, where the $SU(n)$ matrices have $\det = +1$.

$$\det M = e^{i\alpha} = 1 \Rightarrow \alpha = 0 \text{ for } M \in SU(n).$$

This is one constraint, hence the dimension of $SU(n)$ is:

$$\dim. SU(n) = n^2 - 1.$$

5. Symplectic group, $Sp(n)$ - $2n \times 2n$ matrices of the form:

$$\eta = \begin{pmatrix} 0_{n \times n} & \mathbb{1}_{n \times n} \\ -\mathbb{1}_{n \times n} & 0_{n \times n} \end{pmatrix}.$$

η has symplectic form,

$$M^T \eta M = \eta \text{ for } M \in GL(2n, \mathbb{R}).$$

The dimension of $Sp(n) = n(2n+1)$.

Why? E.g. let $n=2 \Rightarrow 4 \times 4$ matrix

$$\eta = \begin{pmatrix} 0_{2 \times 2} & \mathbb{1}_{2 \times 2} \\ -\mathbb{1}_{2 \times 2} & 0_{2 \times 2} \end{pmatrix}.$$

Let $M \in GL(4, \mathbb{R})$ and

$$M = \begin{pmatrix} a_1 & a_2 & a_3 & a_4 \\ b_1 & b_2 & b_3 & b_4 \\ c_1 & c_2 & c_3 & c_4 \\ d_1 & d_2 & d_3 & d_4 \end{pmatrix}$$

$$\begin{aligned} \text{Then, } M^T \eta M &= \begin{pmatrix} a_1 & b_1 & c_1 & d_1 \\ a_2 & b_2 & c_2 & d_2 \\ a_3 & b_3 & c_3 & d_3 \\ a_4 & b_4 & c_4 & d_4 \end{pmatrix} \begin{pmatrix} c_1 & c_2 & c_3 & c_4 \\ d_1 & d_2 & d_3 & d_4 \\ -a_1 & -a_2 & -a_3 & -a_4 \\ -b_1 & -b_2 & -b_3 & -b_4 \end{pmatrix} \\ &\equiv \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix} \end{aligned}$$

There are $(2n)^2 = 16$ equⁿs. However, the diagonal $\text{diag}(M^T \eta M) = 0$, so there's no need to impose equⁿs on the diagonal.

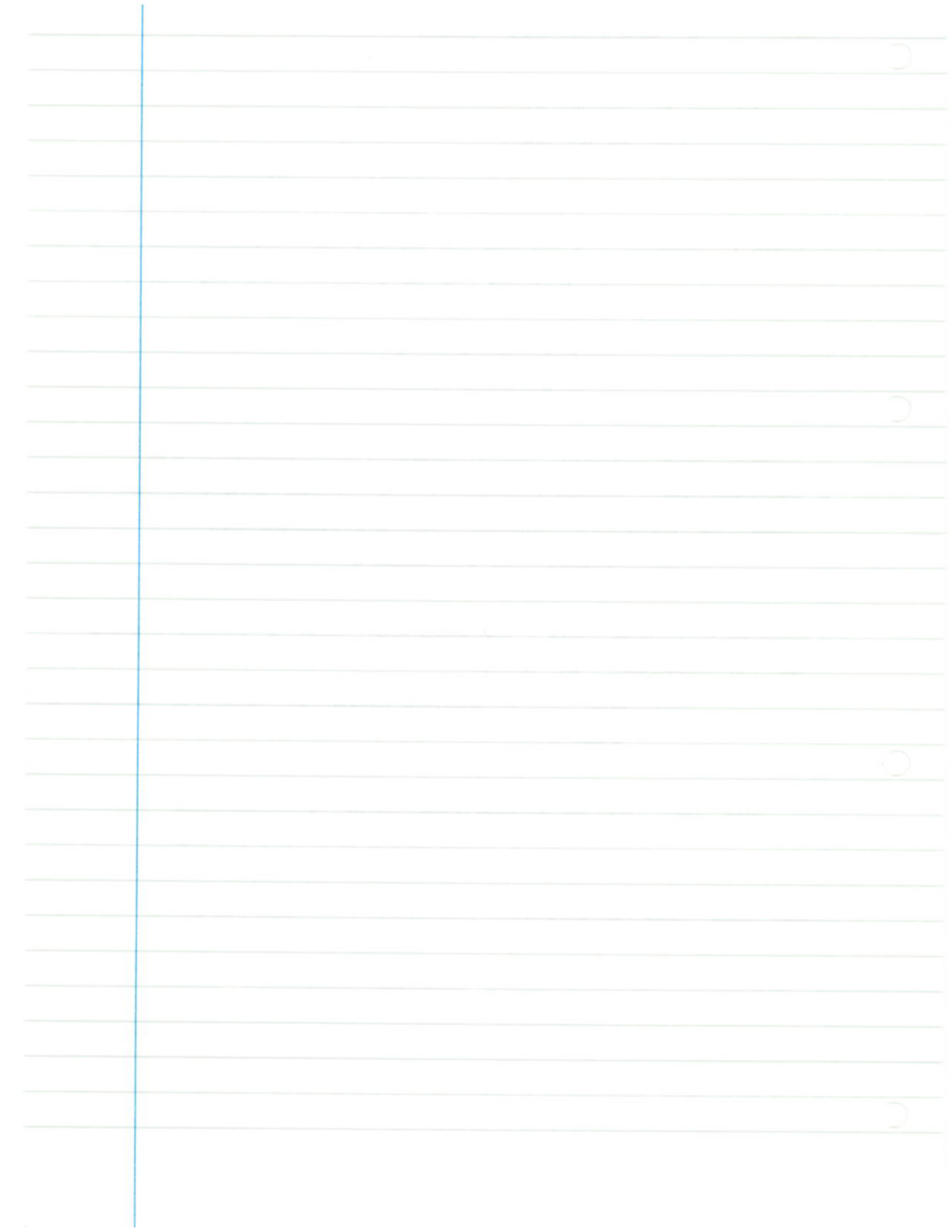
$$\Rightarrow (2n)^2 - 2n \text{ equⁿs.}$$

However, the off-diagonal equⁿs only differ by a factor of (-1)

$\Rightarrow$ there's a doubling of the remaining equⁿs

$$\therefore \text{the no. of indep. equⁿs} = \frac{2n(2n-1)}{2}$$

$$\begin{aligned} \text{So, the dimension} &= (2n)^2 - \frac{2n(2n-1)}{2} \\ &= n(2n+1). \end{aligned}$$



- The dim. of $O(p, q) = \frac{(p+q)(p+q-1)}{2}$
 $\rightarrow$ i.e. the same form as $O(n)$.

The dim. of the Lorentz gp $O(3, 1) = 6$
 $\rightarrow$ 3 rotations and 3 boosts.

2.2 Representations of Gps.

- A repⁿ ρ of gp G is a homo. from $G \rightarrow GL(n, \mathbb{C})$, which preserves the gp multiplication law.
 i.e. $g_1, g_2 \in G$, then $\rho(g_1) \cdot \rho(g_2) = \rho(g_1 g_2)$.
- ρ assigns an $n \times n$ matrix to every element in G .
- n is called the **dimension of the repⁿ**.

E.g. The fundamental repⁿ of the $O(3)$ 3-vec. $\underline{v}$.

$\underline{v} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$, rotation matrix is 3×3 (rotates the vector).

Spin- $1/2$ particles appear in 2dim. repⁿ of $SU(2)$.

The spacetime vectors are 4d. vectors (x, t) , acted by 4×4 matrices of $O(3, 1)$.

- $\exists$ ∞ many repⁿs.

- The gps. discussed are continuous gps.

2.3 Continuous Groups

- Need the concept of a generator.
- Ham. generates t -translations; mom. generates spatial translations.
- Consider a wavefuncⁿ $\psi(x)$, which we shift by "a":

$$\psi(x+a) = \psi(x) + a \psi'(x) + \frac{a^2}{2} \left(\frac{\partial}{\partial x} \right)^2 \psi(x) + \dots$$

$$= \sum_{n=0}^{\infty} \frac{1}{n!} \left(a \frac{\partial}{\partial x} \right)^n \psi(x)$$

$$\triangleq \exp \left(a \frac{\partial}{\partial x} \right) \psi(x)$$

$$\text{let } p = -i\hbar \frac{\partial}{\partial x} \Rightarrow \triangleq \exp \left(\frac{iap}{\hbar} \right) \psi(x)$$

$\Rightarrow$ momentum is a generator of spatial shifts!

- Similarly $H = i\hbar \frac{\partial}{\partial t}$; $e^{-iHt/\hbar} \psi(x,t) = \psi(x,t+t_0)$.
- Every conserved quantity has an associated generator.

- Take $SO(2)$ - look for matrix generators of $SO(2)$.

Parameterise matrix M

$$M = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \quad \text{Rotation of angle } \alpha.$$

look at behaviour at α v. small

$$\begin{aligned} \Rightarrow M &= \begin{pmatrix} 1 & -\alpha \\ \alpha & 1 \end{pmatrix} + O(\alpha^2) \\ &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \alpha \underbrace{\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}}_{X} + O(\alpha^2) \end{aligned}$$

$X \rightarrow$ generator of $SO(2)$ rotations

Then compute $e^{\alpha X}$

$$\begin{aligned} e^{\alpha X} &= \sum_{n=0}^{\infty} \frac{(\alpha X)^n}{n!} \\ &= \sum_{n=0}^{\infty} \underbrace{\frac{(\alpha X)^{2n}}{(2n)!}}_{\text{even powers}} + \sum_{n=0}^{\infty} \underbrace{\frac{(\alpha X)^{2n+1}}{(2n+1)!}}_{\text{odd powers}} \\ &= \sum_{n=0}^{\infty} (\alpha)^{2n} \frac{(-1)^n}{(2n)!} + X \sum_{n=0}^{\infty} \frac{(\alpha)^{2n+1} (-1)^n}{(2n+1)!} \end{aligned}$$

$$= \cos \alpha \cdot \mathbb{1} + X \sin \alpha = M.$$

- X is the generator of rotations in 2 space dim.

3 space-dim. (SO(3)).

- Have 3 angles :

$$\begin{pmatrix} \cos \theta_3 & -\sin \theta_3 & 0 \\ \sin \theta_3 & \cos \theta_3 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{Rotates around the } z\text{-axis.}$$

$$= \mathbb{1}_3 + \theta_3 \underbrace{\begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}}_{\text{generator of rotations around } x_3 \rightarrow X_3} + O(\theta_3^2)$$

$$X_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}, \quad X_2 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}.$$

$$\exp\{\theta_1 X_1 + \theta_2 X_2 + \theta_3 X_3\} = ?$$

Need $[X_i, X_j]$ to figure out exp.

$$\begin{aligned} \text{We find : } [X_1, X_2] &= X_3 \\ [X_2, X_3] &= X_1 \\ [X_3, X_1] &= X_2 \end{aligned}$$

- As differential op. we can say,

$$\underline{L} = \underline{x} \times \underline{p}, \quad \text{where}$$

$$L_x = -i\hbar \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right)$$

$$L_y = -i\hbar \left(z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z} \right)$$

$$L_z = -i\hbar \left(x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)$$

ie. the ang. mom. op. in QM.

$$\Rightarrow [L_i, L_j] = i\hbar \epsilon_{ijk} L_k.$$

L_i act on vector spaces.

- For the matrix analysis we have done,

$$[X_i, X_j] = \epsilon_{ijk} X_k$$

for X_i 3×3 matrices for the 3d repⁿ of $SO(3)$.

- We $\therefore$ have an algebra defined by $[\cdot, \cdot]$.
 $\rightarrow$ Lie Algebra

2.4 The Lie Algebra

Defⁿ: A Lie Algebra is a set of element $\mathcal{A}$, which forms a vector space, with a binary operation,

$$\mathcal{A} \times \mathcal{A} \rightarrow \mathcal{A}.$$

ie. $[\cdot, \cdot] \in \mathcal{A}$.

- They satisfy:

The Lie Algebra

(a) Closure : $A, B \in \mathcal{A}$, $[A, B] \in \mathcal{A}$

(b) Bilinearity : $\alpha, \beta \in \mathbb{C}$ then $[\alpha A + \beta B, C] \stackrel{\Delta}{=} \alpha [A, C] + \beta [B, C]$ w/ $A, B, C \in \mathcal{A}$.

(c) $[A, B] = -[B, A]$

(d) Jacobi Identity ; $A, B, C \in \mathcal{A}$

$$[[A, B], C] + [[B, C], A] + [[C, A], B] = 0.$$

- Algebra generates the rotations around the $\mathbb{1}$.
→ gives local properties.

A grp. contains all the rotations - even large ones.

2.5. The Lie Algebra of $SU(2)$

- Lie Algebra of $SU(2)$ is the same as that of $SO(3)$.
- $[L_i, L_j] = \epsilon_{ijk} L_k$
→ construct repⁿs that obey this algebra.
- Consider a set of lowering/raising op :

$$J_{\pm} = \frac{i}{\sqrt{2}} (L_1 \pm i L_2) \quad , \quad J_3 = i L_3$$

$$\left. \begin{aligned} [J_3, J_{\pm}] &= \pm J_{\pm} \\ [J_+, J_-] &= J_3 \end{aligned} \right\} \begin{aligned} &\mathbb{Z}_2 \text{ symmetry:} \\ &J_+ \leftrightarrow J_- \text{ i.e. } + \leftrightarrow - \\ &\text{symmetry} \end{aligned}$$

This symmetry is called *Weyl symmetry*.

- Construct a set of states in finite dim. vector space.

$$\left. \begin{aligned} J |\phi\rangle \\ J^2 |\phi\rangle \end{aligned} \right\} \begin{aligned} &\text{state} \\ &\text{act op. on states} \end{aligned}$$

Every state is characterised by two quantum no. $|\alpha, m\rangle$

$$\begin{aligned} &\uparrow \quad \quad \uparrow \\ &\epsilon\text{-value} \quad \epsilon\text{-value} \\ &\text{of } J^2 \quad \text{of } J_3. \end{aligned}$$

$$\text{Can do this as } [J^2, J_3] = 0.$$

Note:

$$J^2 = J_+ J_- + J_- J_+ + J_3^2.$$

$$[J^2, J_{\pm}] = 0.$$

- Consider, $J_+ |\alpha, m\rangle$

$$\text{Then, } J^2 J_+ |\alpha, m\rangle = J_+ J^2 |\alpha, m\rangle$$

$$= \alpha J_+ |\alpha, m\rangle$$

$\Rightarrow J_+ |\alpha, m\rangle$ has α E -value under J^2 .

- Under J_3 :

$$\begin{aligned} J_3 J_+ |\alpha, m\rangle &= \left(\overbrace{[J_3, J_+]}^{= J_+} + J_+ J_3 \right) |\alpha, m\rangle \\ &= \cancel{J_+} (m+1) J_+ |\alpha, m\rangle \end{aligned}$$

$\Rightarrow J_+ |\alpha, m\rangle$ has E -value $(m+1)$

$\rightarrow$ raises E -value under J_3 .

- $J_- |\alpha, m\rangle$ has E -value $(m-1)$ under J_3 .

$\rightarrow$ lowers E -value under J_3

Has E -value α under J^2 .

- Finite dim. space $\Rightarrow$ can't raise/lower forever.

Use J_+/J_-

op. to

construct

the irrep's

and to

completely

reduce

red. rep's.

$\downarrow$
useful later
to find
rep's of
general
Lie Algebras.

Have critical value $m=j$ for which

$$J_+ |\alpha, j\rangle = 0.$$

Also, critical $m=j'$ for which,

$$J_- |\alpha, j'\rangle = 0.$$

Jump by integers when raise/lower

$$\Rightarrow j - j' = n, \quad n \text{ integer and } \cancel{\text{non}} \text{ non-negative.}$$

highest spin
cmpt.

lowest spin
cmpt.

- Evaluate:

$$J^2 |\alpha, j\rangle = \left(\underbrace{J_+ J_- + J_- J_+}_{[J_+, J_-] = J_3} + J_3^2 \right) |\alpha, j\rangle$$

$$\downarrow J_+ |\alpha, j\rangle = 0$$

$$= (j^2 + j) |\alpha, j\rangle$$

$$\Rightarrow \alpha = j^2 + j$$

$$[J_-, J_+] = -J_3$$

$$J^2 |\alpha, j'\rangle = \left(J_+ J_- + \underbrace{J_- J_+}_{[J_-, J_+] = -J_3} + J_3^2 \right) |\alpha, j'\rangle$$

$$= (j'^2 - j') |\alpha, j'\rangle \quad \downarrow J_- |\alpha, j'\rangle = 0$$

$$\Rightarrow \alpha = j'^2 - j'$$

$\therefore$ have an equation between the 2 j 's.

$$j(j+1) = j'(j'-1)$$

$$= -j'(1-j')$$

$$\Rightarrow j' = j+1 \quad \text{or} \quad j' = -j \quad \checkmark$$

~~X~~
as defined $j-j' = n \gg 0$.

- The set of m values is going from $-j$ to j in jumps of 1.

- Have $2j+1$ states.

- $n = j - j' = 2j.$

n is twice the spin - The repⁿs of $SU(2)$ (which are finite dimensional) are characterised by a +ve integer $n = 2j$.
 $\rightarrow$ actually non-negative

- n is called the **highest weight** of the repⁿ. of dim $n+1$.

- $-n$ is the **lowest weight** of the repⁿ, by Weyl symmetry.

- There are **irreducible repⁿs**, which are characterised by the highest weight n (non-negative integer)

For $n=0$ 1 state $\rightarrow$ trivial repⁿ
 $\alpha = 0_n.$

$n=1$ 2dim repⁿ $\rightarrow$ spin $-1/2$; σ_i Pauli matrices
simplest, "defining" repⁿ of $SU(2)$.
$$\sigma_i = \left\{ \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right\}.$$

$n=2$ 3-dim repⁿ $\rightarrow$ vec. repⁿ or the **adjoint repⁿ** :

3 = dim. of the algebra

$n=3$ 4-dim repⁿ $\rightarrow$ spin $-3/2$, gravitino.

$n=4$ 5-dim. repⁿ $\rightarrow$ spin 2, graviton -
- traceless second rank sym. tensor.

- Consider a spin $-\frac{1}{2}$ state, V_α $\alpha = 1, 2$.
- We can construct a spin -1 state by taking 2 such states $V_\alpha V_\beta = A_{\alpha\beta}$

→ 3 comp. $V_1^2, V_1 V_2, V_2^2$.

- Can construct spin $\frac{3}{2}$ states w/ 3 such states:

$$A_{\alpha\beta\gamma} = V_\alpha V_\beta V_\gamma$$

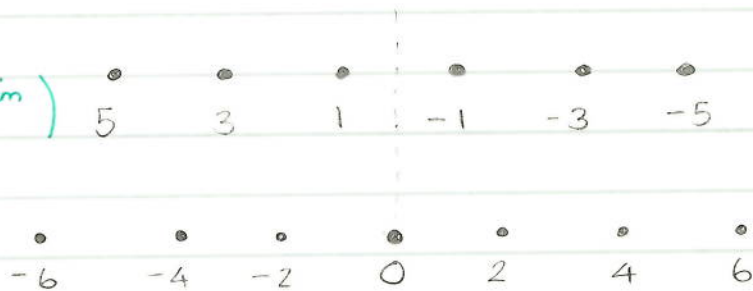
→ $V_1^3, V_1^2 V_2, V_1 V_2^2, V_2^3$ ie. 4 ^{comp.} ~~states~~.
 $\frac{3}{2} \quad \frac{1}{2} \quad -\frac{1}{2} \quad -\frac{3}{2}$

highest weight ← → lowest weight

- A lattice:

⇒ $n = 5$ (as 6-dim repⁿ)

$\times \frac{1}{2}$ to get spin



Spin 3, $n = 7$

~

- The construction of $SU(2)$ irreps. generalises to other compact lie gps.
 - the method used is called the **highest weight construction**.
 - the J_3 values are called **weights**.

2.6 Lie Algebras

$SU(2)$ $[X_i, X_j] = \epsilon_{ijk} X_k$

∞ -many rep's of $SU(2)$ - irreducible.

→ parameterised by a non-neg. integer n ,
where $n = 2j$ (twice spin).

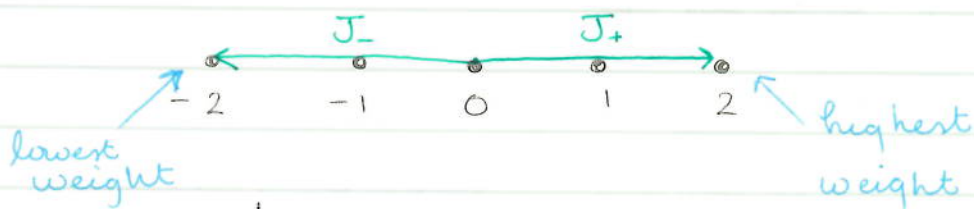
For a fixed n there are $(n+1)$ different states,
parameterised by $-j \leq m \leq j$ in jumps of one.

We call n the **highest weight**, and $2m$ is called the **weights**, which is an integer.



Given n , we can construct all the weights.

E.g. $n = 2$



⇒ two lowering/raising op.

⇒ $2m = -2, 0, 2$ (as $n = 2 \Rightarrow j = 1$).

The set of all points generated by $\alpha = 2$, is the set of all even integers. → **root lattice**.

J^+ - raising op. → **positive root α**

E.g. If $n = 3 \Rightarrow j = 3/2 \Rightarrow$ the set of weights is $-3, -1, 1, 3$

ie the weights are odd
 $\Rightarrow$ 4-dim repⁿ.



This corresponds to half-integer spin.

Odd weights $\Leftrightarrow$ half integer spin

Even weights $\Leftrightarrow$ integer spin

N.B. If α +ve $\Rightarrow$ raising by units of 2

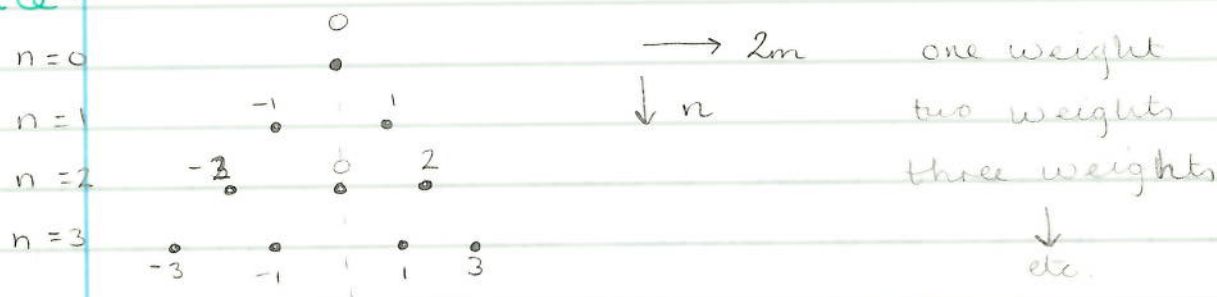
If α -ve $\Rightarrow$ lower by units of 2

- Weyl symmetry : $\mathbb{Z}_2$

$\rightarrow$ for every +ve weight $\exists$ an image which is a -ve weight.

$\rightarrow$ the highest weight has a corresponding lowest weight, which is the lower bound.

Lattice:



$\rightarrow$ generated by the simple roots

The root lattice is a sublattice of the weight lattice.

The root lattice does not contain all weights

$\rightarrow$ introduce the weight lattice, which has all integer points.
 $\rightarrow$ generated by the fundamental weights.

$\rightarrow$ the root lattice is a sublattice of index 2.

- We denote the weight lattice by Λ , and the root lattice by Λ_r

$$\Rightarrow \frac{\Lambda}{\Lambda_r} = \mathbb{Z}_2.$$

For $SU(n)$, this generalises to $\Lambda/\Lambda_r = \mathbb{Z}_n$.

ie. root lattice - take integer multiples of 2
weight lattice - take integer multiples of 1.

$SO(3)$ repⁿ and $SU(2)$ repⁿ

- A rotation op. is given by, say around the 3rd - axis, $\exp(i J_3 \theta)$.

Consider: $e^{i J_3 \theta} |\alpha, m\rangle = e^{im\theta} |\alpha, m\rangle.$

where $\theta \in [0, 2\pi]$ ie. $\theta = \theta + 2\pi$.

$\therefore$ the no. $e^{im\theta} = e^{im(\theta + 2\pi)}$

$$\Rightarrow e^{im2\pi} = 1 \Rightarrow m \text{ integer}$$

- $SO(3)$ repⁿs have integer spin, while $SU(2)$ repⁿs have both integer and half-integer spin.
- As a matrix, we can write,

$$J_3 = \begin{pmatrix} j & & 0 \\ & j-1 & \\ 0 & & \ddots \\ & & & -j \end{pmatrix}, \quad (\text{ie. diagonalised}).$$

highest weight

by a choice of basis $|\alpha, m\rangle$.

- $e^{iJ_3\theta} = \text{diag}(e^{ij\theta}, e^{i(j-1)\theta}, \dots, e^{i(-j)\theta})$.

- A nice feature:

$$\text{Tr } e^{iJ_3\theta} = \sum_{m=-j}^j e^{im\theta}.$$

Define $X = e^{i\theta/2}$.

Then, $\text{Tr } e^{iJ_3\theta} = \sum_{m=-j}^j X^{2m} \equiv f_n(X)$. ↗ character

- Suppose we rotate around another axis, say we pick J_2 .
 $\rightarrow e^{i\beta J_2}$.

$O e^{iH} |x\rangle$

$= O e^{iH} \underbrace{O^{-1}}_{\text{new states}} |x\rangle$ Take: $e^{i\beta J_2} e^{iJ_3\theta} e^{-i\beta J_2}$, but the Tr. of this is preserved i.e. remains as $\text{Tr } e^{iJ_3\theta}$.

- Then, $f_n(X)$ is invariant under conjugation by a matrix $M \in GL(n, \mathbb{C})$.

- The character of an $SU(2)$ repⁿ of highest weight n is given by,

$$f_n(X) = \sum_{m=-n/2}^{n/2} X^{2m}$$

E.g. $n=0$

$n=1$

$n=2$

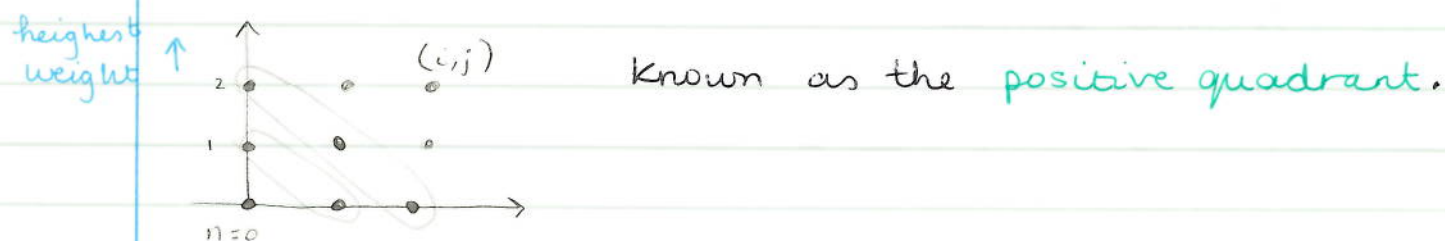
$f_0(X) = 1$

$f_1(X) = X + 1/X$

$f_2(X) = X^2 + 1 + X^{-2}$

} reproduces
the
lattice

- Try to (count) generate all weights for all $SU(2)$ repⁿs.



Pick two dummy variables, t_1, t_2 , s.t. the power of t_1, t_2 is the point on the lattice.

$$\sum_{i=0}^{\infty} \sum_{j=0}^{\infty} t_1^i t_2^j = f(t_1, t_2)$$

$$= \frac{1}{(1-t_1)(1-t_2)}$$

- Set $t_1 = tX$ and $t_2 = \frac{t}{X}$. want to generate highest weight

Then, $f(t_1, t_2) = \frac{1}{(1-tX)(1-t/X)}$

Taylor expand $\downarrow = \sum_{n=0}^{\infty} f_n(X) t^n$ $f(tX, t/X)$ is generating all characters of $SU(2)$.

- t_1 and t_2 are called fugacities.
 t is the fugacity of the h.w., n .
 X is the fugacity for the quantum no. under J_3 .

Example

$$\frac{1}{(1-tx)(1-t/x)} = \underset{n=0}{\uparrow} 1 + \underbrace{(x + 1/x)}_{n=1} t + \underbrace{(x^2 + 1 + 1/x^2)}_{n=2} t^2 + O(t^3)$$

- Hence, we can find all the weights of $SU(2)$ by utilising the character, $f_n(x)$.
- $SU(2)$ Algebra : 3 generators X_i , which satisfy :
 $[X_i, X_j] = \epsilon_{ijk} X_k$.

$SU(3)$ Algebra

- 8 generators (as $n^2 - 1$)
 $\rightarrow$ Gell-Mann matrices

$$\lambda_1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \lambda_2 = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\lambda_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \lambda_4 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix}$$

$$\lambda_5 = \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix} \quad \lambda_6 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\lambda_7 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \quad \lambda_8 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix} \frac{1}{\sqrt{3}}$$

- Traceless generators as $\det(e^{i\lambda_a \theta}) = 1$.
 $\rightarrow$ condition on $SU(3)$.

Also $\lambda_a^\dagger = \lambda_a$ and $\text{Tr}(\lambda_a \lambda_b) = 2 \delta_{ab}$.
 $\Rightarrow$ the $SU(3)$ matrices are unitary $\Rightarrow \det = +1$
 where $a = 1, \dots, 8$

We can define $T_a = -\frac{1}{2} \lambda_a$ and $T_a^\dagger = -T_a$
 anti-hermitian

Then, $[T_a, T_b] = f_{abc} T^c$
 structure constants
 for the algebra

- We have 3 different $SU(2)$ subalgebras:

Need
these to
construct
the repⁿs

$$\lambda_1, \lambda_2, \lambda_3$$

$$\lambda_4, \lambda_5, \underbrace{\frac{\sqrt{3}}{2} \lambda_8 + \frac{1}{2} \lambda_3}_{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}}$$

$$\lambda_6, \lambda_7, \frac{\sqrt{3}}{2} \lambda_8 - \frac{1}{2} \lambda_3$$

- 3 dim. repⁿs of the $SU(3)$ algebra
 $\rightarrow$ the defining repⁿ.
- We have 2 diagonal matrices - λ_3, λ_8

$$\Rightarrow [\lambda_3, \lambda_8] = 0$$

$\Rightarrow$ all of the states can be parameterised by E -values of λ_3, λ_8 .

- λ_3, λ_8 form a maximally commuting set of matrices $\therefore$ any state is characterised by their E -values.
 $\rightarrow \therefore$ will have 2 highest weights or a highest weight vector that is 2-dim.

Cartan Subalgebra

$\rightarrow$ diagonal generators

- The set of maximally commuting generators.
- The **rank** is the no. of such generators.

No. of roots
 $= \dim - \text{rank}$
 $\Rightarrow$ No. of roots for $SU(3)$
 $= 8 - 2 = 6$.

$\rightarrow$ rank of $SU(3) = 2 \Rightarrow \text{rep}^n$ are 2 dim.
 $\rightarrow$ rank of $SU(n) = n - 1$.

- Use new basis as more convenient for computations.

Diagonal elements are E -values of the 3dim rep^n

Pick $h_1 = \begin{pmatrix} \frac{1}{2} & 0 & 0 \\ 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 \end{pmatrix}, h_2 = \begin{pmatrix} \frac{\sqrt{3}}{2} & 0 & 0 \\ 0 & \frac{\sqrt{3}}{2} & 0 \\ 0 & 0 & -\sqrt{3} \end{pmatrix}$

$\rightarrow$ diagonal, $[h_1, h_2] = 0$.

$\rightarrow$ all the rep^n s will be E -values of h_1, h_2 .

- Raising / lowering op:

The weights are $\therefore (\frac{1}{2}, \frac{\sqrt{3}}{6}), (-\frac{1}{2}, \frac{\sqrt{3}}{6})$ and $(0, -\frac{\sqrt{3}}{3})$. This forms the weight

linear combination of generators eg. like $J_{\pm}$.

$$e_+^1 = \begin{pmatrix} 0 & 1/\sqrt{2} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad e_-^1 = \begin{pmatrix} 0 & 0 & 0 \\ 1/\sqrt{2} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$e_+^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1/\sqrt{2} \\ 0 & 0 & 0 \end{pmatrix} \quad e_-^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1/\sqrt{2} & 0 \end{pmatrix} = (e_+^2)^T$$

$$e_+^3 = \begin{pmatrix} 0 & 0 & 1/\sqrt{2} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad e_-^3 = (e_+^3)^T$$

→ traceless, not hermitian.

The roots are the differences of weights as the corresponding generators must take us from one weight to another.

- Replace $h_i \rightarrow H_i$ as repⁿs we construct will be $n \times n$, not 3×3 .

Explicitly compute for abc.

$$[H_1, H_2] = 0$$

$E_{\pm}^1$ not in max. commuting algebra as it only commutes w/ H_2 and not also H_1 .

$$[H_1, E_{\pm}^1] = \pm E_{\pm}^1 \quad [H_2, E_{\pm}^1] = 0.$$

$$[H_1, E_{\pm}^2] = \mp \frac{1}{2} E_{\pm}^2 \quad [H_2, E_{\pm}^2] = \pm \frac{\sqrt{3}}{2} E_{\pm}^2$$

SU(2) subalgebra

$$[H_1, E_{\pm}^3] = \pm \frac{1}{2} E_{\pm}^3 \quad [H_2, E_{\pm}^3] = \pm \frac{\sqrt{3}}{2} E_{\pm}^3.$$

Like $[J_+, J_-] = J_3$

$$[E_+^1, E_-^1] = H_1$$

$$[E_+^2, E_-^2] = \frac{\sqrt{3}}{2} H_2 - \frac{1}{2} H_1$$

$$[E_+^3, E_-^3] = \frac{\sqrt{3}}{2} H_2 + \frac{1}{2} H_1$$

Commutation relation w/ Cartan subalg.

"like" terms

mixed terms

$$[E_+^1, E_+^2] = \frac{1}{\sqrt{2}} E_+^3$$

$$[E_-^1, E_-^2] = -\frac{1}{\sqrt{2}} E_-^3$$

$$[E_+^1, E_-^3] = -\frac{1}{2} E_-^2$$

$$[E_-^1, E_+^3] = \frac{1}{\sqrt{2}} E_+^2$$

$$[E_+^2, E_-^3] = \frac{1}{\sqrt{2}} E_-^1$$

$$[E_-^2, E_+^3] = -\frac{1}{\sqrt{2}} E_+^1$$

- Each commutation has a meaning that we need to figure out.
- Denote a state by $|\lambda_1, \lambda_2, p, q\rangle$
highest weight
E-values of H_1, H_2

$$\text{So, } H_1 |\lambda_1, \lambda_2, p, q\rangle = p |\lambda_1, \lambda_2, p, q\rangle$$

$$H_2 |\lambda_1, \lambda_2, p, q\rangle = q |\lambda_1, \lambda_2, p, q\rangle$$

What are the allowed values of p, q and how many states?

$$E_{\pm}^1 |\lambda_1, \lambda_2, p, q\rangle$$

raises p by ± 1

$$= C_{\lambda_1, \lambda_2, p, q} |\lambda_1, \lambda_2, (p \pm 1), q\rangle$$



Use $H_1, H_2, E_{\pm}^2 | \rangle$

to find
E-values

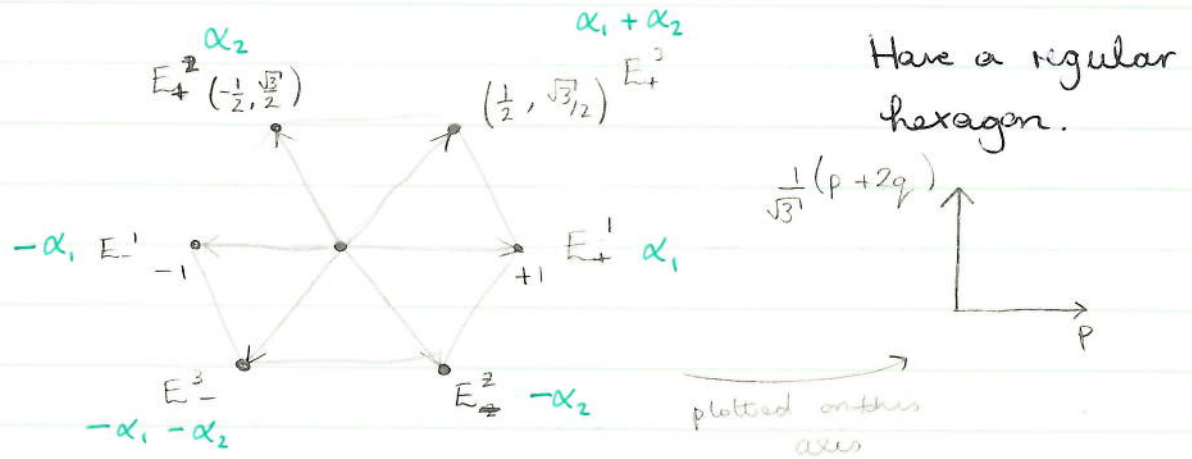
$$\hookrightarrow E_{\pm}^2 |\lambda_1, \lambda_2, p, q\rangle$$

raises p by $\mp \frac{1}{2}$ and q by $\pm \frac{\sqrt{3}}{2}$

$$= C'_{\lambda_1, \lambda_2, p, q} |\lambda_1, \lambda_2, p \mp \frac{1}{2}, q \pm \frac{\sqrt{3}}{2}\rangle$$

$E_{\pm}^3$ changes (p, q) to $(p, q) \pm (\frac{1}{2}, \frac{\sqrt{3}}{2})$.

Equilateral Δ s.



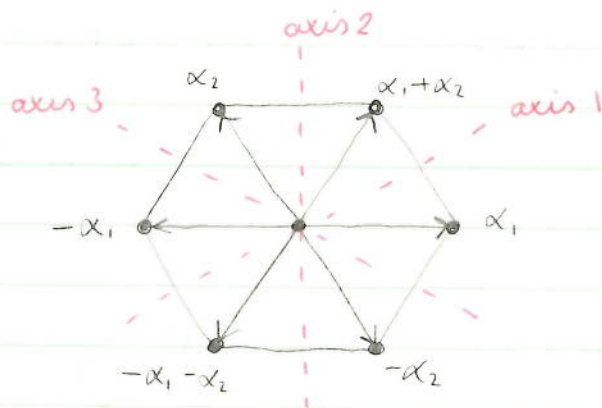
The +ve roots correspond to raising op.

3 positive roots } 3 SU(2) subalgebras
3 negative roots }

The highest weight has the property that we cannot raise it.

$\Rightarrow \alpha_1, \alpha_2, \alpha_1 + \alpha_2$
 $-\alpha_1, -\alpha_2, -\alpha_1 - \alpha_2$ by Weyl sym.

α_1, α_2 are the root vectors



Rotations of $2\pi/3$ + reflections in y-axis leave the set of weights invariant

--- Weyl reflection

} action by +ve roots

SU(2) associated w/ each root direction

- H_1, H_2 have zero weight (ie. middle/centre of hexagon).
- $\{\alpha\}$ are the vectors we add as we raise and lower.

- Have 3 $SU(2)$ subalgebras
 - one from $\alpha_1, -\alpha_1$
 - generated by $\pm \alpha_2$
 - and the final by $\pm(\alpha_1 + \alpha_2)$.

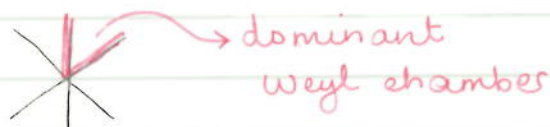
The subalgebras do not commute amongst themselves.

- Each $SU(2)$ has a Weyl reflection
 - can start with one pt (eg α_1) and can get all the rest from Weyl reflection
 - eg. can get $(-\alpha_1, -\alpha_2)$ from $-\alpha_2$.
- The hexagon has a reflection symmetry
 - Weyl gp. is S_3 i.e. the permutation group in 3 elements

N.B. Not including rotation symmetry. Reflections (successive reflections) do not commute amongst themselves.

- Using Weyl symmetry bypasses the lengthy $[\cdot, \cdot]$ calculations we had to do.

- We have 6 wedges



→ if we know rep^n is one wedge, we know rep^n in all wedges due to Weyl sym.

- Wedges are called **Weyl chambers**.

- What's special about the dominant Weyl chamber?
- Require highest weight that vanishes on action by the +ve roots.
- For a given highest weight λ_1, λ_2 , we demand :

$$E_+^i |\lambda_1, \lambda_2, p = \lambda_1, q = \lambda_2\rangle = 0$$

- The dominant chamber contains all the possible highest weights.
- Suppose we are not in the dom. chamb.



Acting by α_2 moves us to dom chamb



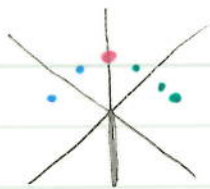
all the highest weights live here
Applying +ve roots here keeps us in this chamber.

- 4 different regions of a chamber.
 - (i) pts. inside the chamber
 - (ii) on the boundary 2 times
1 pt. (origin).

- Pick the pt. at the origin
 $\Rightarrow (\lambda_1, \lambda_2 = 0)$ trivial repⁿ of dim 1.

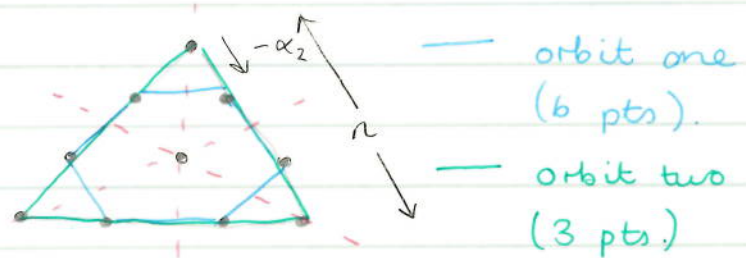
Pick highest weight to be along the vertical axis

→ apply Weyl reflection



- highest weight
- application of α_2
- application of α_1

Should look like

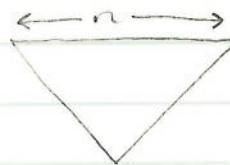
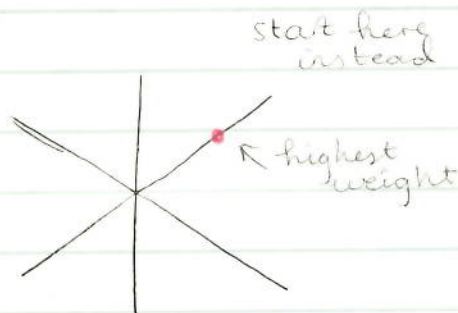


This is a 10d repⁿ

- We have a set of triangles with edge of length n and the no. of pts. is $\frac{(n+1)(n+2)}{2}$

E.g. in above example, $n=3$.

- A class of repⁿs of $SU(3)$ is parameterised of dim $\frac{(n+1)(n+2)}{2}$
- $n=0$ gives the trivial repⁿ.

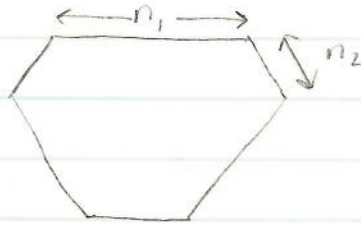


$$\text{No. of pts} = \frac{(n+1)(n+2)}{2}$$

- Pick pt. inside wedge eg. $\alpha_1 + \alpha_2$.
 $\rightarrow$ 8-dim repⁿ $\rightarrow$ 6 pts in orbit, 2 in the centre of zero weight.

- For highest weights inside the wedge has the shape of the polygon is a hexagon.

Can have:



$$\text{No. of pts in } \frac{(n_1+1)(n_2+1)(n_1+n_2+2)}{2}$$

- Triangle is a special case where $n_2 = 0$.
- All irrepⁿs of $SU(3)$ are parameterised by 2 highest weights n_1, n_2 of dimension:

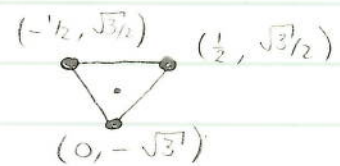
$$\frac{(n_1+1)(n_2+1)(n_1+n_2+2)}{2}$$

Examples

- $[n_1, n_2] = 0 \Rightarrow \in$ family of Δ s.

has length 1 and three pts.

$\Rightarrow$ 3dim repⁿ.



The pts. are exactly the values for (p, q) .

- $[0, 1]$



Also 3dim.

- $[2, 0]$



6pts.

Multiplicity of each weight is the same on each layer. For $n_1 > n_2$,

- $[0, 2]$



there are $n_2 + 1$ hexagonal layers and then the layers become triangular. For hexagonal layers, the multiplicity $\uparrow$ by 1 moving inwards; Δ layers ^{all} have multiplicity $(n_2 + 1)$.

- $[2, 1]$



$$\dim = \frac{3 \cdot 2 \cdot 5}{2} = 15$$

i.e. need 15 pts on diagram

Multiplicity of 2.

$$\begin{aligned} \text{No. of pts} &= 3 \times 3 + 3 \times 2 = 15 \\ &\Rightarrow 15 \text{ dim-rep}^n. \end{aligned}$$

~

$$\text{SU}(3) \text{ has dim } 8 = \underset{\substack{\uparrow \\ \text{rank}}}{2} + \underset{\substack{\uparrow \\ \text{+ve roots}}}{3} + \underset{\substack{\uparrow \\ \text{-ve roots}}}{3}$$



$\uparrow$ are 2-dim vectors

$\rightarrow$ No. of simple roots is equal to the rank.

- We have 2 simple roots α_1, α_2 .

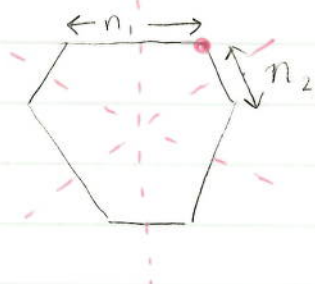
$\rightarrow$ all other roots are a linear combination of the simple roots.

If a weight is annihilated by the generation of all the simple roots, it is the highest weight of the repⁿ.

- An irrepⁿ of $\text{SU}(3)$ is parameterised by 2 non--ve integers, n_1 and n_2 of dim.

$$\frac{(n_1+1)(n_2+1)(n_1+n_2+2)}{2}.$$

These rep^n 's are characterised by hexagons.



- highest weight $\rightarrow$ always in the dominant Weyl chamber.

----- Weyl symmetry

- n_1, n_2 parameterise the size of the hexagon, and define the dim of the rep^n .
- Consider $\text{rep}^n [1, 0]$

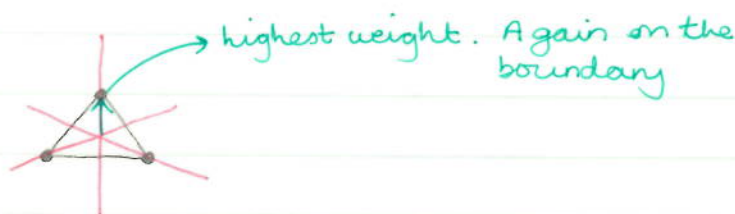
Fundamental
 rep^n



Define vector $\nearrow \lambda_1$ (a 2 vector).

$\text{Rep}^n [0, 1]$

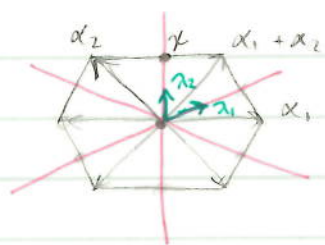
Anti-fundamental
 rep^n



Call $\nearrow \lambda_2$.

$\therefore \lambda_1$ is the highest weight of $[1, 0]$ and λ_2 the highest weight of $[0, 1]$.

N.B. λ_i are "smaller" vectors than α_i .



$$\left. \begin{aligned} \lambda_1 &= \frac{2}{3} \alpha_1 + \frac{1}{3} \alpha_2 \\ \lambda_2 &= \frac{1}{3} \alpha_1 + \frac{2}{3} \alpha_2 \end{aligned} \right\} \text{fundamental weights}$$

So, define $A = \frac{1}{3} \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$

$$\alpha_1 = 2\lambda_1 - \lambda_2$$

$$\alpha_2 = -\lambda_1 + 2\lambda_2$$

transit from

$\Lambda_w \leftrightarrow \Lambda_r$ w/

matrix A .

and $\lambda_i = A_{ij} \alpha_j$ the λ_i are the weight vec.

Any vector in the dom. Weyl chamber is just a linear combination of λ_1, λ_2 .

The highest weight is $\lambda = n_1 \lambda_1 + n_2 \lambda_2$

$\Rightarrow \lambda_1, \lambda_2$ are called fundamental weights.

- The weight lattice $\Lambda_w = \sum_{\text{integer}} \lambda_1 + \sum \lambda_2$

- The root lattice $\Lambda_r = \sum \alpha_1 + \sum \alpha_2$.

Cyclic gp. of order n .

$$\mathbb{Z}_n = \frac{\mathbb{Z}}{n\mathbb{Z}}$$

$\rightarrow$ compare Λ_w and Λ_r : $\frac{\Lambda_w}{\Lambda_r} = \mathbb{Z}_3$.

$$= \{0, 1, \dots, n-1\}$$

w/ addition modulo n .

1 pt. in $\Lambda_r \Rightarrow 3$ pts. in Λ_w and vice versa.

$$\text{E.g. } \omega^n = 1 \Rightarrow \omega = e^{2\pi i k/n}$$

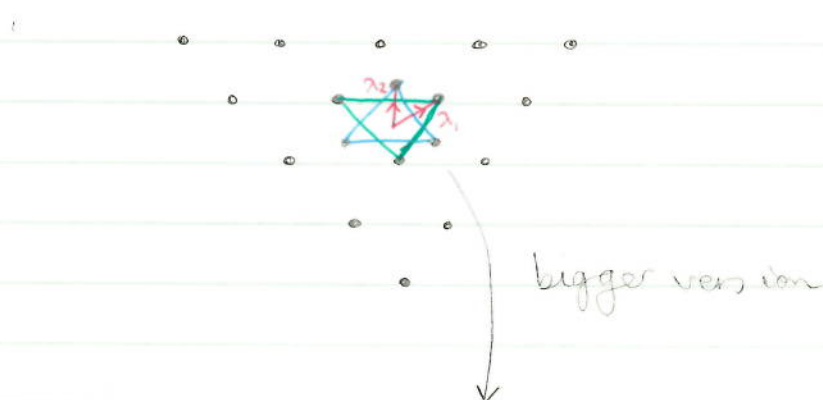
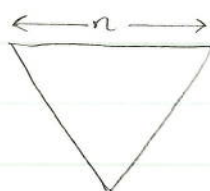
where $k=0, 1, \dots, (n-1)$

i.e. Reflecting pts. at λ_2 gives us a total of 3 pts.

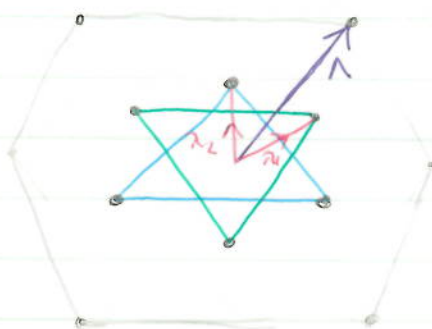
But reflecting from pt. directly above λ_2 (λ in the diagram above) gives 6 pts

Examples of Cyclic Group

Repⁿs $[n, 0]$



∇ is 3 dim repⁿ
 ∇ is the other
 3 dim repⁿ.



$$\Lambda = \lambda_1 + \lambda_2 = \alpha_1 + \alpha_2$$

Just get our hexagon
 again

The set of repⁿs given by $\lambda = n\lambda$,

- Consider a 3-vec. $V_i \in \mathbb{C}$, $i = 1, 2, 3$.

let $a_{ij} = V_i V_j$; how many components for a ?
 $\rightarrow$ 3x3 symmetric $\Rightarrow a_{ij}$ has 6 compts.

Let $a_{ijk} = V_i V_j V_k$

→ 27 compts. , but only 10 independ.

Let $a_{i_1 \dots i_n} = V_{i_1} \dots V_{i_n} \Rightarrow \frac{(n+1)(n+2)}{2}$ independ compts.

This is because a is an n^{th} -rank symmetric tensor.

We compute the n^{th} sym. product $\text{Sym}^n[1,0] = [n,0]$

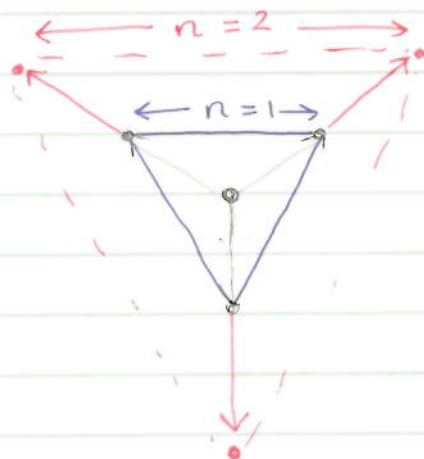
→ n^{th} sym. product of the 3 dim repⁿ.

ie to find dimension of $\triangleleft^n$ we count the no. of pts. in the triangle.

- Consider the 3 weights of fundamental repⁿ of $SU(3)$. Take all possible multiplications

Constructed a $\triangle$ of $n=2$ from $n=1$.

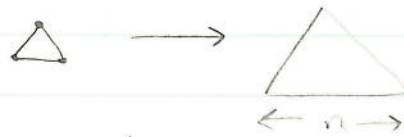
Note: Vectors $\nearrow$ are of the same length as $\triangle$ are equilateral. Same w/ $\nwarrow$.



where $\nearrow$ and $\nwarrow$ are vectors.

Just used Λ_1 here and then applied successively to get the n -length triangle

- The $\text{Sym}^n [0,1] = [0,n]$.



- Introduce lower and upper indices:

w^i , $i = 1, 2, 3$ antifundamental index

$w_i \Rightarrow$ fundamental index.

- Now consider:

Tensor product

$$a_{ij}^j = v_i w^j$$

$\uparrow$ $\uparrow$
 $[1,0]$ $[0,1]$

different from a_{ij}, a_{ijk} from before.

→ Now we have 9 compts.

→ Draw the lattice for this

Just add the E-values of the rep's being tensor producted, then decompose.



ie we addⁿ.
 ↑
 from multiplying antipodal pts.



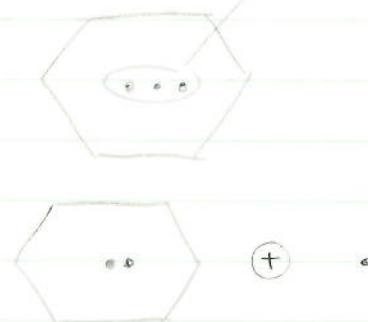
$$3 \quad 3 \quad 8 \quad 1$$

$$[1,0] [0,1] = [1,1] + [0,0]$$

tensor product

3 antiquarks
 3 quarks

8 gluons
 (mesons).



dim 8

dim 1

trivial
 repⁿ

SU(3) Algebra :

- 8 generators that transform in the adj. repⁿ
- 2 Cartan gen.
- 3 +ve roots $\rightarrow$ 2 simple roots, 2 fundamental weights
3 -ve roots.
- The SU(3) repⁿ is given by two integer no. $[n_1, n_2]$

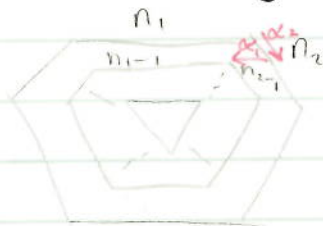


The dim. of $[n_1, n_2] = \frac{(n_1+1)(n_2+1)(n_1+n_2+2)}{2}$

- The highest weight λ of the repⁿ $[n_1, n_2]$ is given by :

$$\lambda = n_1 \lambda_1 + n_2 \lambda_2$$

- Have diminishing hexagons layer by layer :



Eventually there will be a layer that is a Δ

Outer layer has multiplicity 1, next layer has 2 etc. until we hit the Δ , then the multiplicity remains constant.

- Start with λ (highest weight) then act with vectors inwards to get to the centre.
 $\rightarrow$ also use Weyl sym.

Symmetric Products

$$\text{Sym}^n [1, 0] = [n, 0]$$

Highest weight λ_1 in $[1, 0] \Rightarrow n\lambda_1$ in $[n, 0]$.

$$\text{Sym}^n [0, 1] = [0, n].$$

$$\text{Sym}^n \begin{array}{c} \leftarrow 1 \\ \nabla \end{array} = \begin{array}{c} \leftarrow n \\ \nabla \end{array}$$

$$\text{Sym}^n \begin{array}{c} \triangle \\ 1 \end{array} = \begin{array}{c} \triangle \\ n \end{array}$$

Tensor Product

$$\begin{array}{c} \triangle \\ 1 \end{array} \begin{array}{c} \nabla \\ 1 \end{array} = \begin{array}{c} \text{hexagon} \\ \vdots \end{array} + \bullet$$

dim 3 3 = 8 + 1

$[1, 0]$ - fundamental repⁿ dim 3.

$[0, 1]$ - antifundamental repⁿ dim $\underline{3}$ or $\overline{3}$.

$$\Rightarrow 3 \times \underline{3} = 8 + 1.$$

$\rightarrow$ adjoint repⁿ