

TENSOR PRODUCT DECOMPOSITION OF IRREPS AND YT

Label irreps of dimension "d" by:

- ① Vector notation
- ② \underline{d}
- ③ Young Tableaux and YT label

One can start with the defining rep and use tensor products to build all higher dimensional representation.

When tensoring two irreps with \underline{d}_1 and \underline{d}_2 the resulting representation will in general be reducible. It can be decomposed into irreps s.t.:

$$\underline{d}_1 \underline{d}_2 = \sum_m \underline{d}_m$$

How do we do this?

Start with tensoring two defining reps and decompose using invariant tensors. Use this rule to build any higher dimensional representation. Systemise the procedure using YT.

** Notation **

If a representation \underline{d} is realised as $v^i \mapsto (\rho)^i_j v^j$, then its conjugate representation $\bar{\underline{d}}$ will be realised as $(v^+)_i \mapsto (v^+)_j (\rho^+)^j_i$ where $(v^+)_i = (v^i)^*$ and $(\rho^+)^j_i = (\rho^i_j)^*$. The connection to Dirac's notation is obvious

$$(v^+)_i \mapsto (v^+)_j (\rho^+)^j_i$$

$$\Rightarrow \cancel{(v^i)^*} \mapsto (v^j)^* (\rho^i_j)^*$$

$$\Rightarrow (v^i)^* \mapsto (\rho^i_j)^* (v^j)^*$$

- $SU(2)$ examples:

$$\rho_z = \begin{pmatrix} a & -b^* \\ b & a^* \end{pmatrix} \text{ with } aa^* + bb^* = 1$$

One can show that the only invariant tensor with indices on the same level is ϵ^{ij} with $\epsilon^{12} = -\epsilon^{21} = 1$ and $\epsilon^{11} = \epsilon^{22} = 0$.
Do this by explicitly showing that:

$$(\rho_z)^i{}_k (\rho_z)^j{}_l \epsilon^{kl} = \epsilon^{ij}$$

$$\begin{aligned} \underline{2} \times \underline{2} : V^i U^j &= \frac{1}{2} \epsilon^{ij} \epsilon_{mn} V^m U^n + \left(V^i U^j - \frac{1}{2} \epsilon^{ij} \epsilon_{mn} V^m U^n \right) \\ &= \frac{1}{2} (V^i U^j - V^j U^i) + \frac{1}{2} (V^i U^j + V^j U^i) \\ &= V^{[i} U^{j]} + V^{(i} U^{j)} \end{aligned}$$

$$\Rightarrow \underline{2} \times \underline{2} = \underline{1} + \underline{3} \quad // \text{ with the scalar being } \phi = \epsilon_{mn} V^m U^n$$

- $SU(3)$ examples:

The invariant tensor is now ~~the~~ ϵ_{abc}

$$\begin{aligned} \underline{3} \times \underline{3} : V^a U^b &= \frac{1}{2} \epsilon^{abc} \epsilon_{cgh} V^g U^h + \left(V^a U^b - \frac{1}{2} \epsilon^{abc} \epsilon_{cgh} V^g U^h \right) \\ &= V^{[a} U^{b]} + V^{(a} U^{b)} \end{aligned}$$

$$\Rightarrow \underline{3} \times \underline{3} = \underline{\bar{3}} + \underline{6} \quad // \text{ with the } \underline{\bar{3}} \text{ being } W_c = \epsilon_{cgh} V^g U^h$$

$$\underline{3} \times \underline{\bar{3}} : Z^a W_b = \frac{1}{3} \delta^a_b Z^c W_c + \left(Z^a W_b - \frac{1}{3} \delta^a_b Z^c W_c \right)$$

$$\Rightarrow \underline{3} \times \underline{\bar{3}} = \underline{1} + \underline{8} \quad // \text{ with the } \underline{1} \text{ being } \phi = Z^c W_c$$

SU(N)

In general, the irreps of ~~SU(N)~~ are all possible (anti)symmetrisations of the indices and the Young Tableaux are simply a schematic way of doing this.

Elements are:

- Symmetric in rows
- Antisymmetric in columns \Rightarrow column with N boxes is a singlet

The following rules apply to SU(2) or SU(3) but they are easily extended to SU(N): Tensor diagram A or diagram B

- (i) Put a's in the top row of B and b's in the second row of B.
- (ii) Take the boxes from the top row of B and put them on A to form "allowed" tableaux with no a's on the same column.
- (iii) Take the boxes from the second row of B and put them on the resulting diagrams to form "allowed" tableaux with no b's on the same column.
- (iv) Reading from right to left, from the top row to the bottom, need to have $\# a's \geq \# b's$

• SU(2) examples:

In SU(2) a column with 2 boxes will be a singlet and thus the most general tableaux is:

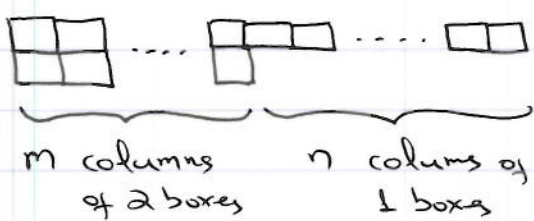
$\underbrace{\square \square \dots \square \square}_{n \text{ columns of } 1 \text{ box}}$: label as (n) with dimension $\underline{n+1}$

$$\underline{2} \times \underline{2} = \square \times \square = \begin{array}{|c|} \hline a \\ \hline \end{array} + \begin{array}{|c|c|} \hline a & a \\ \hline \end{array} = \bullet + \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} = \underline{1} + \underline{3} //$$

$$\begin{aligned} \underline{3} \times \underline{3} &= \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} \times \begin{array}{|c|c|} \hline a & a \\ \hline \end{array} = \begin{array}{|c|c|c|} \hline \square & a & a \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & a \\ \hline a & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline a & a \\ \hline \end{array} \\ &= \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} + \bullet = \underline{5} + \underline{3} + \underline{1} // \end{aligned}$$

• $SU(3)$ examples:

In $SU(3)$ a column with 3 boxes is a singlet and thus the most general tableaux is:


 : Label by (n, m) with dimension:

$$d = \frac{(n+1)(m+1)(n+m+2)}{2}$$

$$\underline{3} \times \underline{3} = \begin{array}{|c|} \hline \square \\ \hline \end{array} \times \begin{array}{|c|} \hline a \\ \hline \end{array} = \begin{array}{|c|} \hline a \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & a \\ \hline \end{array} = \underline{\bar{3}} + \underline{6} //$$

$$\underline{3} \times \underline{\bar{3}} = \begin{array}{|c|} \hline \square \\ \hline \end{array} \times \begin{array}{|c|} \hline a \\ \hline b \\ \hline \end{array} \rightarrow \begin{array}{|c|c|} \hline \square & a \\ \hline \end{array} \rightarrow \begin{array}{|c|c|} \hline \square & a \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & b \\ \hline \end{array} + \begin{array}{|c|} \hline a \\ \hline b \\ \hline \end{array}$$

$$= \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} + \cdot = \underline{8} + \underline{1} //$$

Try to slow:

$$\underline{8} \times \underline{8} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} \times \begin{array}{|c|c|} \hline a & a \\ \hline b & \end{array}$$

$$= \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \end{array} + \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \end{array} + \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \end{array} + 2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} + \cdot$$

$$= \underline{27} + \underline{10} + \underline{\bar{10}} + \underline{8} + \underline{8} + \underline{1} //$$

The calculation of tensor products of $SO(N)$ and $Sp(N)$ are more involved since there are other invariant tensors as well (δ^{ij} for $SO(N)$ and Ω^{ij} for $Sp(N)$). Keeping in mind that δ^{ij} is symmetric while Ω^{ij} is antisymmetric the calculation of two defining reps become:

$$SU(N): V^i U^j = V^{[i} U^{j]} + V^{(i} U^{j)}$$

$$N^2 = \left[\frac{N(N-1)}{2} \right] + \left[\frac{N(N+1)}{2} \right]$$

$$SO(N): V^i U^j = V^{[i} U^{j]} + \left(V^{(i} U^{j)} - \frac{1}{N} \delta^{ij} \delta_{kl} V^k U^l \right) + \frac{1}{N} \delta^{ij} \delta_{kl} V^k U^l$$

$$N^2 = \left[\frac{N(N-1)}{2} \right] + \left[\frac{N(N+1)}{2} - 1 \right] + [1]$$

$$Sp(N): V^i U^j = \left(V^{[i} U^{j]} - \frac{1}{N} \Omega^{ij} \Omega_{kl} V^k U^l \right) + V^{(i} U^{j)} + \frac{1}{N} \Omega^{ij} \Omega_{kl} V^k U^l$$

$$N^2 = \left[\frac{N(N-1)}{2} - 1 \right] + \left[\frac{N(N+1)}{2} \right] + [1]$$