

Data-Driven Geometric Identification of Operating-Point-Induced Changes in Modal Structure of Black-Box IBRs

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Introduction and Motivation

Detailed IBR models are often unavailable, and only black-box representations are accessible at **specific operating points**.

Data-driven methods are promising, but operating condition variations can induce **changes in system structure**, altering system dynamics.

This work identifies structural changes using a **geometric parametrisation** of the **singular value decomposition (SVD)**, enabling the detection of **structurally coherent** operating regions.

Geometric parametrisation

Using the SVD, the continuity of a transfer function due to a parameter change α can be expressed as

$$\Delta \mathbf{G}_\alpha(j\omega) = \mathbf{U}_\alpha \left[\Sigma_\alpha - \underbrace{(\mathbf{U}_\alpha^H \mathbf{U}_0)}_{U\text{-alignment}} \Sigma_0 \underbrace{(\mathbf{V}_\alpha \mathbf{V}_0^H)^H}_{V\text{-alignment}} \right] \mathbf{V}_\alpha^H$$

Then, the **continuity** and **smoothness** of a transfer function depends on:

- **Variations** in the singular values
- **Alignment** of the left- and right-singular vectors

Similar structural conditions lead to similar vector alignments

Bloch sphere of a projection matrix \mathbf{P}_k

$$\mathbf{r}_k(\omega) = \begin{bmatrix} x_k(\omega) \\ y_k(\omega) \\ z_k(\omega) \end{bmatrix} = \begin{bmatrix} \mathbf{P}_{k,12} + \mathbf{P}_{k,21} \\ \mathbf{P}_{k,12} - \mathbf{P}_{k,21} \\ \mathbf{P}_{k,11} - \mathbf{P}_{k,22} \end{bmatrix}$$

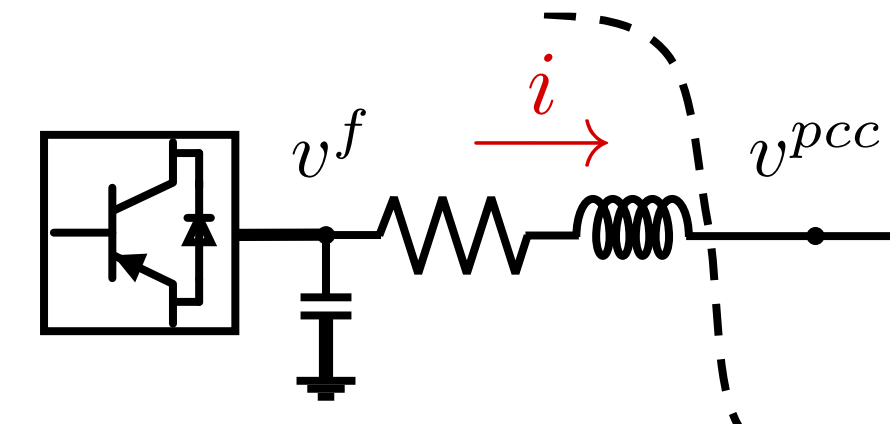
For a set of operating points, the singular vectors of the IBR admittance $Y(j\omega)$ define a set of projection matrices \mathbf{P}_1 and \mathbf{P}_2

Each projection can be mapped onto the surface of a unit **Bloch sphere**, yielding trajectories \mathbf{r}_1 and \mathbf{r}_2

A combined geometric trajectory can then be defined as a weighted superposition of the two singular trajectories

Clustering of modal trajectories based on the geometric trajectories and singular values

Study case and results



Single IBR equivalent model connected to the grid through a coupling impedance

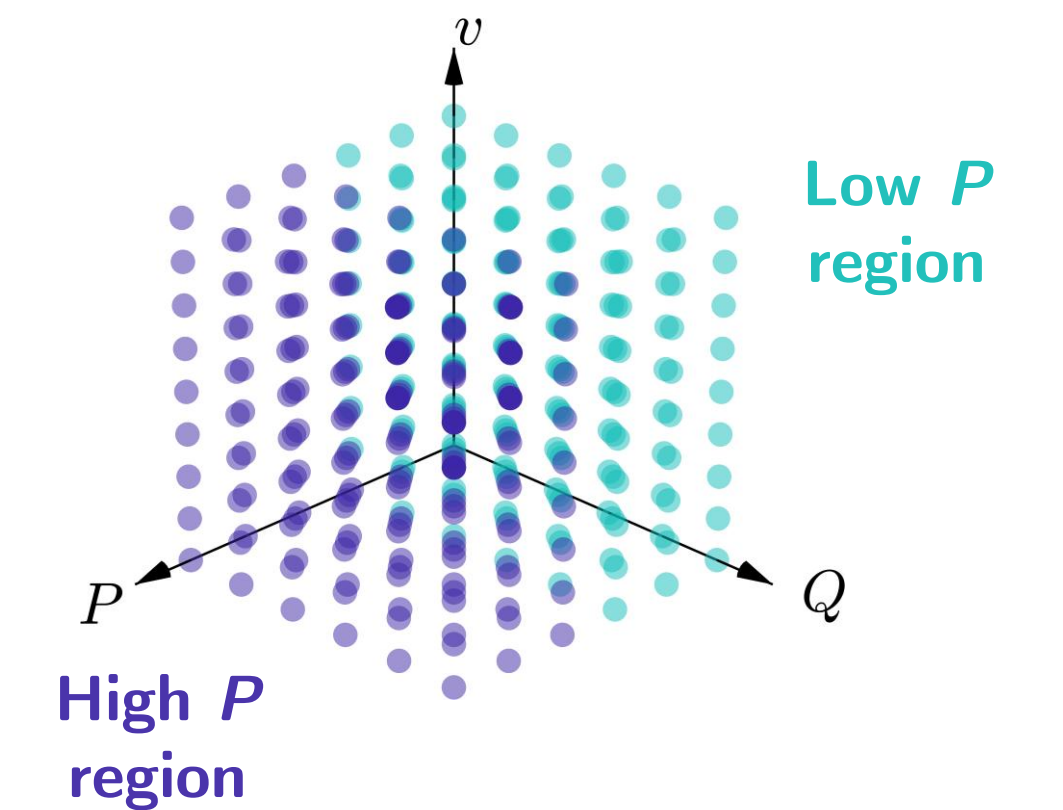
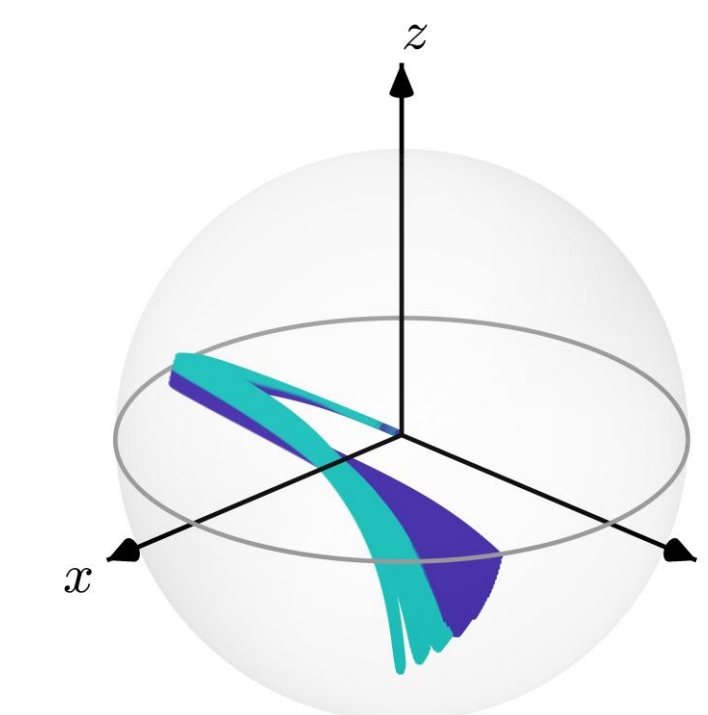
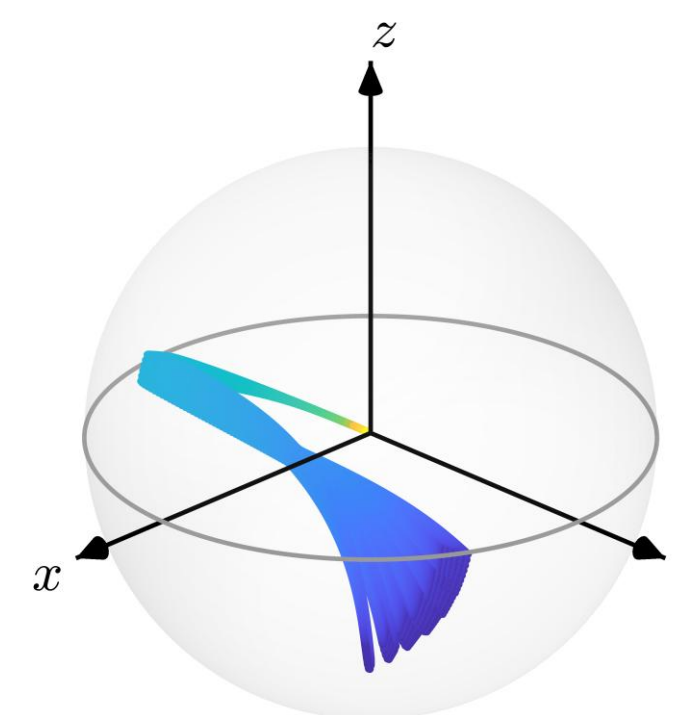
- **Control modes:** Grid following and grid forming
- **Frequency scan range:** 0.15 - 3500 Hz
- **Operating conditions:** 324 combinations of (P, Q, V)

Frequency trajectories

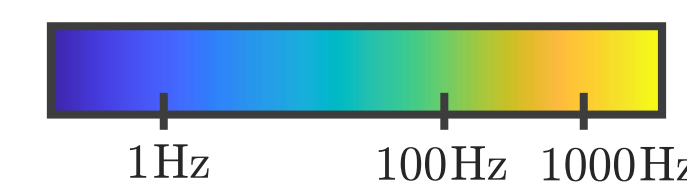
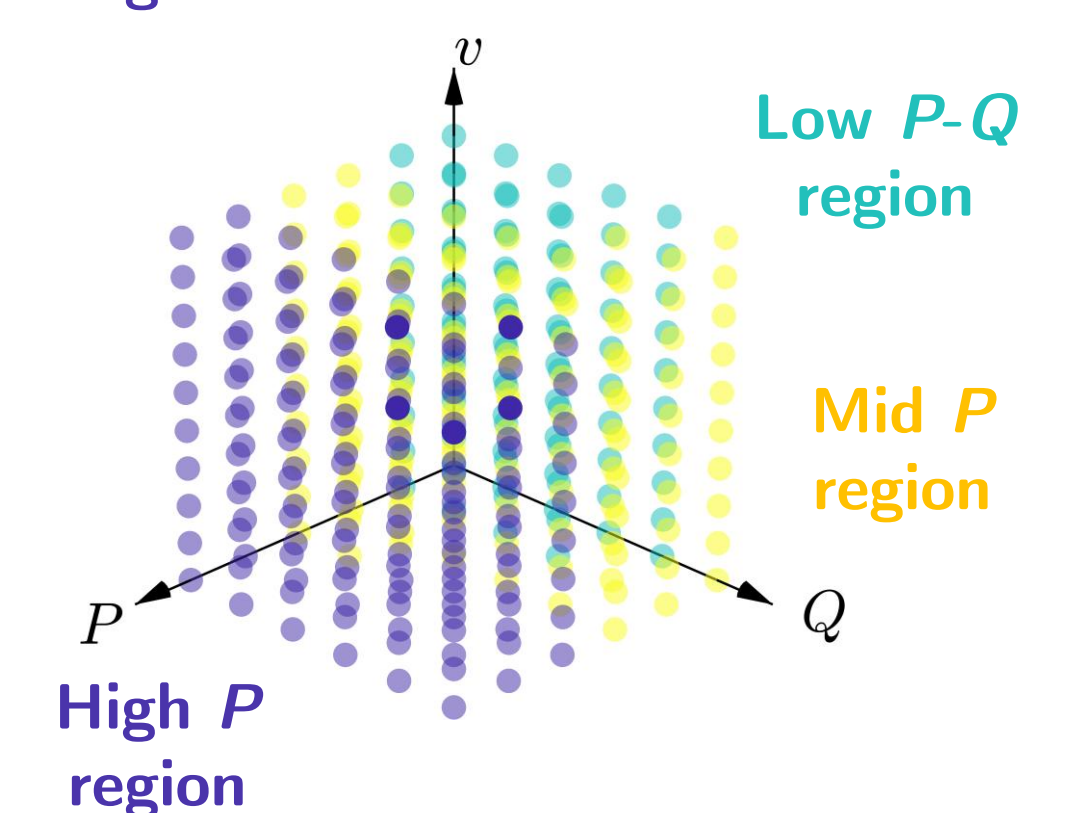
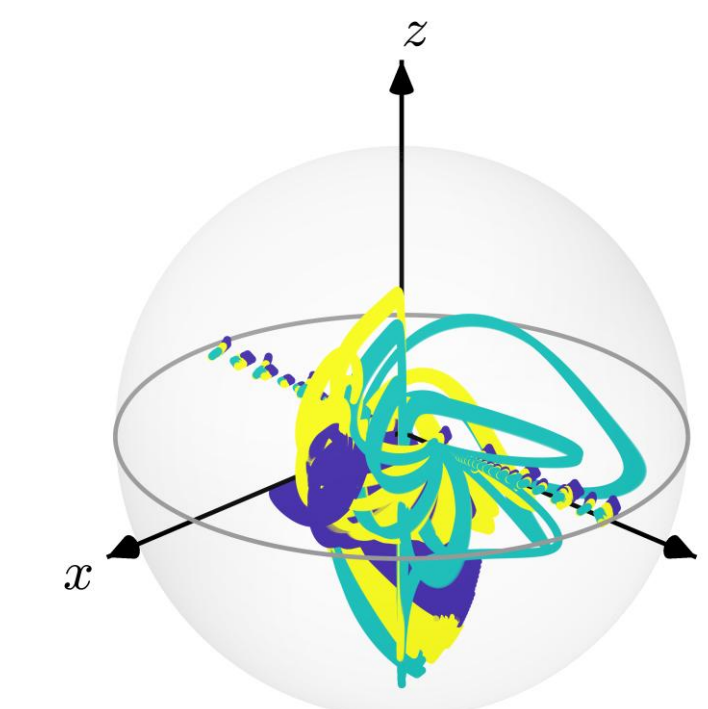
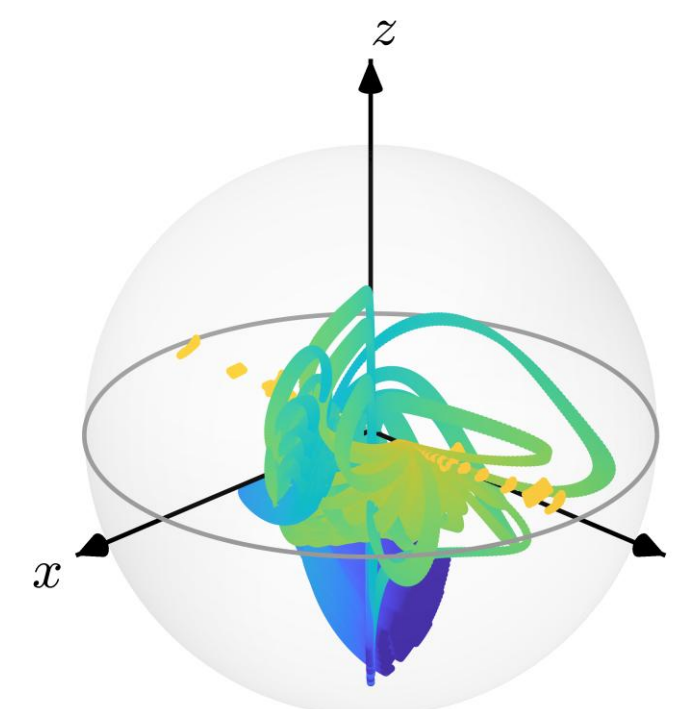
Clustering

Operating regions

Grid forming



Grid following



Applications

- **Identification** of coherent dynamic operating regions and system sensitivities
- **Enhanced data-driven** estimation of IBR models via dataset partition